

## 3.1 Determinants (Introduction)

Key idea: The notion of determinant we saw for a  $2 \times 2$  matrix can be extended to any  $n \times n$  matrix. Much like in  $2 \times 2$  setting,  $\det(A)$  tells us a lot about an  $n \times n$  matrix  $A$ , namely if  $A$  is invertible or not. We will see in section 3.3 the geometric information  $\det(A)$  gives about the transformation  $\vec{x} \mapsto A\vec{x}$ .

Recall that a  $2 \times 2$  matrix is invertible if it is row-equivalent to  $I_2$ , so

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \sim \begin{bmatrix} a & b \\ 0 & d - bc/a \end{bmatrix} \sim \begin{bmatrix} a & 0 \\ 0 & ad - bc \end{bmatrix} \sim \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \text{ so long as } ad - bc \neq 0.$$

$a \neq 0$

i.e., so long as  $\det(A) \neq 0$ .

We now extend the definition of  $\det(A)$  to all  $n \times n$  matrices and study this quantity in detail. (Note: the book (pg 166) gives an algebraic justification for higher dimensional determinants much like we did for  $2 \times 2$ . The algebra is a touch messy, so we omit this.)

Def: Let  $A = [a_{ij}]$  be an  $n \times n$  matrix, we define the determinant of  $A$ , written  $\det(A)$  as follows: if  $n=1$ ,  $\det(A) = \det([a]) = a$ .

if  $n \geq 2$ , define  $A_{ij}$  to be the  $(n-1) \times (n-1)$  matrix obtained by deleting the  $i^{\text{th}}$  row and  $j^{\text{th}}$  column of  $A$ , then

$$\det(A) = a_{11} \det(A_{11}) - a_{12} \det(A_{12}) + a_{13} \det(A_{13}) - \dots + (-1)^n a_{nn} \det(A_{nn}).$$

Notice this is an alternating sum of determinants for smaller matrices. To compute  $\det(A)$ , we need first know  $\det(A_{ij})$  and so on. In practice, this involves a lot of computation but we will see methods to make calculation much easier.

Ex Compute the determinant of

$$A = \begin{bmatrix} 1 & 5 & 0 \\ 2 & 4 & -1 \\ 0 & -2 & 0 \end{bmatrix}$$

$$A_{11} = \begin{bmatrix} 4 & -1 \\ -2 & 0 \end{bmatrix}$$

$$A_{12} = \begin{bmatrix} 2 & -1 \\ 0 & 0 \end{bmatrix}$$

$$A_{13} = \begin{bmatrix} 2 & 4 \\ 0 & -2 \end{bmatrix}$$

$$\det(A) = 1 \cdot \det(A_{11}) - 5 \det(A_{12}) + 0 \det(A_{13})$$

so we need find  $A_{11}, A_{12}, A_{13}$  and their determinants

For brevity we write  $|A|$  in place of  $\det(A)$ :

$$|A_{11}| = \begin{vmatrix} 4 & -1 \\ -2 & 0 \end{vmatrix} = 0 - 2 = -2, |A_{12}| = \begin{vmatrix} 2 & -1 \\ 0 & 0 \end{vmatrix} = 0 - 0 = 0, |A_{13}| = \begin{vmatrix} 2 & 4 \\ 0 & -2 \end{vmatrix} = -4.$$

$$\text{So } |A| = a_{11}|A_{11}| - a_{12}|A_{12}| + a_{13}|A_{13}| = 1(-2) - 5(0) + 0(-4) = \boxed{-2}$$

Notice how the presence of 0's in  $A$  simplify the calculation, the next fact allows us to fully exploit the structure of  $A$  to aid in finding determinants.

**Def:** For an  $n \times n$  matrix  $A$ , the  $(i,j)$ -cofactor of  $A$  is:  $C_{ij} = (-1)^{i+j} \det(A_{ij})$ .

**Fact:** The determinant of  $A$  is equal to the sum of the cofactors across any row or column, i.e.

$$\text{for any } i: \det(A) = a_{i1}C_{i1} + a_{i2}C_{i2} + \dots + a_{in}C_{in}$$

and,

$$\text{for any } j: \det(A) = a_{1j}C_{1j} + a_{2j}C_{2j} + \dots + a_{nj}C_{nj}.$$

**Note:** We call such a sum a cofactor expansion across the  $i^{\text{th}}$  row ( $j^{\text{th}}$  column). The sum is always alternating with minus signs determined by  $a_{ij}$  position in  $A$  i.e.  $\begin{bmatrix} + & - & + & - & \dots \\ - & + & - & + & \dots \\ + & - & + & - & \dots \\ \vdots & & \ddots & & \ddots \end{bmatrix}$

**Ex]** Recompute  $\det A$  for

$$A = \begin{bmatrix} 1 & 5 & 0 \\ 2 & 4 & -1 \\ 0 & -2 & 0 \end{bmatrix} \leftarrow a_{31} + \leftarrow a_{32} - \leftarrow a_{33} +$$

$$\begin{array}{c} \xrightarrow{a_{11}} \\ \xrightarrow{a_{12}} \\ \xrightarrow{a_{13}} \end{array} \begin{bmatrix} + & - & + & - & \dots \\ - & + & - & + & \dots \\ + & - & + & - & \dots \\ \vdots & & \ddots & & \ddots \end{bmatrix}$$

This follows from the def. of  $C_{ij}$ :  
 $(-1)^{i+j} = \begin{cases} +1 & i+j \text{ even} \\ -1 & i+j \text{ odd.} \end{cases}$

using a cofactor expansion down the third column.

$$\det A = a_{31}C_{31} + a_{32}C_{32} + a_{33}C_{33} = (0)(-1)^{3+1} \begin{vmatrix} 2 & 4 \\ 0 & -2 \end{vmatrix} + (-1)(-1)^{3+2} \begin{vmatrix} 1 & 5 \\ 0 & -2 \end{vmatrix} + (0)(-1)^{3+3} \begin{vmatrix} 1 & 5 \\ 2 & 4 \end{vmatrix}$$

$$= 0 + (-2) + 0 = \boxed{-2} \quad \checkmark$$

We conclude with another example of an informed choice of a cofactor expansion. We will see that triangular matrices are particularly nice to compute the determinant.

Ex Compute  $\det(B)$  where  $B = \begin{bmatrix} 3 & -2 & 8 & 9 & -6 \\ 0 & 2 & -5 & 7 & 3 \\ 0 & 0 & 1 & 5 & 0 \\ 0 & 0 & 2 & 4 & -1 \\ 0 & 0 & 0 & -2 & 0 \end{bmatrix}$ . We choose a cofactor expansion involving many zeros: column 1.

$$\det(B) = 3C_{11} + 0C_{21} + 0C_{31} + 0C_{41} + 0C_{51}$$

$$= 3(-1)^{1+1} \begin{vmatrix} 2 & -5 & 7 & 3 \\ 0 & 1 & 5 & 0 \\ 0 & 2 & 4 & -1 \\ 0 & 0 & -2 & 0 \end{vmatrix} = 3 \cdot (2 \begin{vmatrix} 1 & 5 & 0 \\ 2 & 4 & -1 \\ 0 & -2 & 0 \end{vmatrix}) - 0 \begin{vmatrix} \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots \end{vmatrix} = 3 \cdot 2 \cdot \begin{vmatrix} 1 & 5 & 0 \\ 2 & 4 & -1 \\ 0 & -2 & 0 \end{vmatrix}$$

another cofactor expansion

$$= 3 \cdot 2 \cdot (-2) \quad \text{from above} \\ = \boxed{-12}.$$

Notice that as we expand down the first and second columns, we simply multiply a smaller determinant by the diagonal entries.

If every column of  $B$  was like the first two, the determinant would have simply been the product of the diagonal entries.

Fact: If  $A$  is a triangular matrix, then  $\det A$  is the product of the diagonal entries of  $A$ .

On a numerical note: the number of calculations it takes to compute a determinant of a random  $n \times n$  matrix is roughly  $n!$  ... which is huge. To compute a  $25 \times 25$  determinant requires  $1.5 \times 10^{25}$  operations. So, if we do a trillion operations a second, we'll need 500,000 years.

So how does Maple compute this in less than a second? There are some properties of  $\det(A)$  that severely ease our computational task, and we heavily exploit that last fact.